## A Markov Reward Model Checker

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# Verification of Markov Reward Models

## MRMs are underneath:

- Reward extensions of stochastic process algebras
- Stochastic reward nets
- Etc.



# Allowed properties

## PRCTL extends PCTL with:

- The expected reward rate at a time instant
- Interpretending of the second seco
- The instantaneous reward at a time instant
- The expected accumulated reward at a time instant

## CSRL extends CSL with

- PRCTL
- The probability to reach one of the goal states (via indicated allowed states) within time t while having earned an accumulated reward that does not exceed r is larger than p

## Examples

### Example: PRCTL

 $\mathcal{Y}^3_{[2,5]} \Phi$  - the expected accumulated cost in  $\Phi\text{-states}$  within 3 hops is between 2 and 5



#### Example: CSRL

 $\mathcal{P}_{\geq 0.3}(\phi \, \mathcal{U}_{(23,\infty)}^{\leq 4} \, \psi)$  - a  $\Psi$ -state is reached with probability at least 0.3 in at most 4 time units along an  $\Phi$ -path with total cost > 23

# Implementation

## Algorithms:

PRCTL

Sparse matrix - compressed row, compressed column

PCTL

CSL

CSRL

- (Hansson and Jonsson, 1994)
- (Andova et al., 2003)
- (Baier et al., 2003)
  - Discretization (Tijms and Veldman, 2000), Uniformization (Qureshi and Sanders, 1996)

### Improvements:

- Search for bottom strongly connected components
- On-the-fly steady state detection
- Path graph representation

# A command-line tool

### Input files:

- .tra the probability/rate matrix
- .lab the state-labeling
- .rew the state rewards
- .rewi the impulse rewards

### Example

```
46:)ewi410:/> ../../bin/mrmc csrl
csrl_unif_state_impulse_01.tra csrl_unif_state_impulse_01.lab
csrl unif state impulse 01.rew csrl unif state impulse 01.rewi
Running in the CSRL model checking mode.
States=5. Transitions=11
Space Occupied:: 1424 Bytes.
Type 'help' to get help.
>>P{>0.1}[ Sup U[0,50][0,3000] failed ]
State = 0, Probabilty = 5,087386e-03, Error Bound = 5,325909e-10
State = 1. Probabilty = 1.230380e-02. Error Bound = 4.466197e-10
State = 2, Probabilty = 1.000000e-00, Error Bound = 4.147793e-12
State = 3, Probabilty = 1.000000e-00, Error Bound = 4.147793e-12
State = 4, Probabilty = 1.000000e-00, Error Bound = 4.147793e-12
Result: ( 5.087386125019004e-03, 1.230379607517677e-02,
9,9999999999958522e-01, 9,999999999958522e-01,
9.9999999999958522e-01)
time to compute: 953 micro sec(s)
states = {3, 4, 5, }
>>quit
```



# CSL logic: $\Phi U^{[0,t]} \Psi$



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# CSRL logic: $\Phi \cup_{[0,r]}^{[0,t]} \Psi$



#### A Markov Reward Model Checker

#### Appendix

#### Andova, S., Hermanns, H., and Katoen, J.-P.: 2003,

#### Discrete-time rewards model-checked,

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#### Hansson, N. and Jonsson, B.: 1994, A logic for reasoning about time and probability, Formal Aspects of Computing 6, 512

#### Qureshi, M. A. and Sanders, W. H.: 1996,

A New Methodology for Calculating Distributions of Reward Accumulated During a Finite Interval., in Proceedings of the 26th International Symposium on Fault-Tolerant Computing, pp 116–125, Sendai, Japan

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#### Tijms, H. C. and Veldman, R.: 2000, A fast algorithm for the transient reward distribution in continuous-time Markov chains, in Oper. Res. Lett., Vol. 26, pp 155–158

A Markov Reward Model Checker Appendix

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Result: ( 5.087386125019004e-03, 1.230379607517677e-02,
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